



**February 2011**  
**Signal Converters**

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# About Signal Converters

The signal converter components provide conversions between the various signal types in ADS Ptolemy and process scalar or matrix data that are integer, double precision floating point (real), fixed-point (fixed), or complex values. Each component accepts a specific class of signal and outputs a resultant signal. These components do not accept any matrix class of signal.

If a component receives another class of signal, the received signal is converted automatically to the signal class specified as the input of the component. Auto conversion from a higher to a lower precision signal class can result in loss of information.

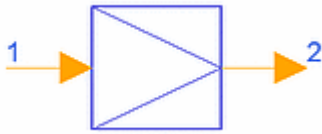
The auto conversion from timed, complex or floating-point (real) signals to a fixed signal uses a default bit width of 54 bits with the minimum number of integer bits needed to represent the value in twos complement representation. For example, the auto conversion of the floating-point (real) value of 1.0 creates a fixed-point value with precision of 2.52; a value of 0.5 would create one of precision of 1.53. For details on conversions between different classes of signals, refer to *Conversion of Data Types* (ptolemy) in the *ADS Ptolemy Simulation* documentation.

Some components operate with fixed-point numbers. These components use one or more parameters that define the characteristics of the fixed-point processing. These parameters include: *OverflowHandler*, *OutputPrecision*, *RoundFix*, *ReportOverflow*, and others.

For details, refer to *Parameters for Fixed-Point Components* (ptolemy) in the *ADS Ptolemy Simulation* documentation.



## BitsToInt



**Description** Bits to Integer

**Library** Signal Converters

**Class** SDFBitsToInt

**C++ Code**

### Parameters

Name	Description	Default	Type	Range
nBits	number of bits read per execution	4	int	[1, ∞)

### Pin Inputs

Pin	Name	Description	Signal Type
1	input		int

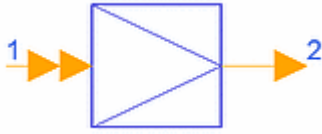
### Pin Outputs

Pin	Name	Description	Signal Type
2	output		int

### Notes/Equations

1. The integer input sequence is interpreted as a bit stream in which any nonzero value is interpreted as to mean a *one* bit. BitsToInt consumes nBits successive bits from the input, packs these into an integer, and outputs the resulting integer. The first received bit becomes the most significant bit of the output.
2. If nBits is larger than the integer word size, the first bits received is lost; if nBits is smaller than the wordsize minus one, the output integer is always non-negative.
3. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

## BusToNum



**Description** Bus to Number

**Library** Signal Converters

**Class** SDFBusToNum

**C++ Code**

### Parameters

Name	Description	Default	Type
Previous	previous value of output	0	int

### Pin Inputs

Pin	Name	Description	Signal Type
1	input		multiple int

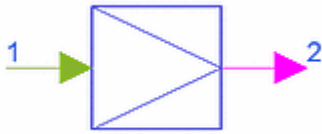
### Pin Outputs

Pin	Name	Description	Signal Type
2	output		int

### Notes/Equations

1. BusToNum accepts a number of input bit streams, where this number should not exceed the wordsize of an integer. Each bit stream has integer data with values 0, 3, or anything else; these are interpreted as binary 0, tri-state, or 1, respectively. When the component simulates, it reads one input bit from each input.
2. If any of the input bits is tri-stated, the output is the previous output (or the initial value of the Previous parameter if the simulation is the first one). Otherwise, the bits are assembled into an integer word, assuming twos complement encoding, and sign extended. The resulting signed integer is sent to the output.
3. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

## CxToFix



**Description** Complex to Fixed-Point

**Library** Signal Converters

**Class** SDFCxFix

**Derived From** SDFFix

**C++ Code**

### Parameters

Name	Description	Default	Type
OverflowHandler	output overflow characteristic: wrapped, saturate, zero_saturate, warning	wrapped	enum
ReportOverflow	simulation overflow error report option: DONT_REPORT, REPORT	REPORT	enum
RoundFix	fixed-point computations, assignments, and data type conversions option: TRUNCATE, ROUND	TRUNCATE	enum
OutputPrecision	precision of output in bits and accumulation	2.14	precision

### Pin Inputs

Pin	Name	Description	Signal Type
1	input	Input complex type	complex

### Pin Outputs

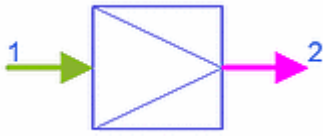
Pin	Name	Description	Signal Type
2	output	Output fix type	fix

### Notes/Equations

1. CxToFix converts a complex input to a fixed-point output. The magnitude of the complex input is calculated and then converted to a fixed-point number with the given OutputPrecision.
2. If the fixed-point operations cannot fit into the precision specified, overflow occurs with the overflow characteristic specified by OverflowHandler. If ReportOverflow = REPORT, after the simulation has finished the number of overflow errors (if any) is reported. RoundFix identifies whether fixed-point calculations are truncate or round method. For details, refer to *Parameters for Fixed-Point Components* (ptolemy) in the *ADS Ptolemy Simulation* documentation.
3. This component uses twos-complement arithmetic; OutputPrecision parameter values must specify at least 1 bit to the left of the decimal place (used as a sign bit).
4. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).



## CxToFix\_M



**Description** Complex to Fixed-Point Matrix

**Library** Signal Converters

**Class** SDFCnToFix\_M

**Derived From** SDFFix

### Parameters

Name	Description	Default	Type
OverflowHandler	output overflow characteristic: wrapped, saturate, zero_saturate, warning	wrapped	enum
ReportOverflow	simulation overflow error report option: DONT_REPORT, REPORT	REPORT	enum
RoundFix	fixed-point computations, assignments, and data type conversions option: TRUNCATE, ROUND	TRUNCATE	enum
OutputPrecision	precision of output in bits and accumulation	2.14	precision

### Pin Inputs

Pin	Name	Description	Signal Type
1	input		complex matrix

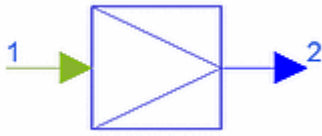
### Pin Outputs

Pin	Name	Description	Signal Type
2	output		fix matrix

### Notes/Equations

- CxToFix\_M converts an input complex matrix to a fixed-point matrix by calculating the magnitude of the elements in the input matrix and then converting the magnitudes to fixed-point numbers with the given OutputPrecision.
- If the fixed-point operations cannot fit into the precision specified, overflow occurs with the overflow characteristic specified by OverflowHandler. If ReportOverflow = REPORT, after the simulation has finished the number of overflow errors (if any) is reported. RoundFix identifies whether fixed-point calculations are truncate or round method.  
For details, refer to *Parameters for Fixed-Point Components* (ptolemy) in the *ADS Ptolemy Simulation* documentation.
- For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

## CxToFloat



**Description** Complex to Floating-Point

**Library** Signal Converters

**Class** SDFCxToFloat

**C++ Code**

### Pin Inputs

Pin	Name	Description	Signal Type
1	input	Input complex type	complex

### Pin Outputs

Pin	Name	Description	Signal Type
2	output	Output float type	real

### Notes/Equations

1. CxToFloat converts a complex input to a floating-point (real) output. The output is the absolute of the input complex number.

*output* – *abs(input)*

Given a complex number

$$C = a + bj$$

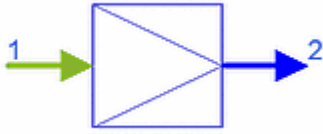
the *abs()* function is defined as

$$abs(C) = \sqrt{a^2 + b^2}$$

The complex number is not converted to floating-point by discarding the imaginary component as might be expected.

2. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

## CxToFloat\_M



**Description** Complex to Floating-Point(real) Matrix

**Library** Signal Converters

**Class** SDFCxToFloat\_M

**Derived From** MatrixBase

### Pin Inputs

Pin	Name	Description	Signal Type
1	input		complex matrix

### Pin Outputs

Pin	Name	Description	Signal Type
2	output		real matrix

### Notes/Equations

1. CxToFloat\_M converts an input complex matrix to a floating-point (real) matrix. The conversion results in a floating-point (real) matrix with entries that are the absolute value of each corresponding entry of the complex matrix being converted.

$$\text{FloatMatrix entry}(i) = \text{abs}(\text{ComplexMatrix entry}(i))$$

Where for a complex number

$$C = a + bj$$

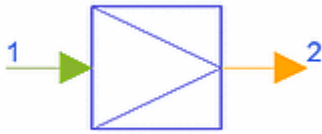
the abs() function is defined as

$$\text{abs}(C) = \sqrt{a^2 + b^2}$$

The complex entries are not converted to floating-point by discarding the imaginary component as might be expected.

2. For general information regarding signal converter components, refer to the *About Signal Converters* (sigconverters).

## CxToInt



**Description** Complex to Integer

**Library** Signal Converters

**Class** SDFCxToInt

**C++ Code**

### Pin Inputs

Pin	Name	Description	Signal Type
1	input	Input complex type	complex

### Pin Outputs

Pin	Name	Description	Signal Type
2	output	Output int type	int

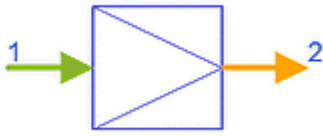
### Notes/Equations

1. CxToInt converts a complex input to an integer output. The output is generated by first converting the complex number to a floating-point (real) (see *CxToFloat* (sigconverters)) and then casting the result:  

$$output = int(abs(input))$$
2. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).



## CxToInt\_M



**Description** Complex to Integer Matrix

**Library** Signal Converters

**Class** SDFCxToInt\_M

**Derived From** MatrixBase

### Pin Inputs

Pin	Name	Description	Signal Type
1	input		complex matrix

### Pin Outputs

Pin	Name	Description	Signal Type
2	output		int matrix

### Notes/Equations

1. CxToInt\_M converts an input complex matrix to an integer matrix. The conversion results in an integer matrix with entries that are the integer portion of the absolute value of each corresponding entry of the complex matrix being converted.

$$\text{IntegerMatrix entry}(i) = \text{int}(\text{abs}(\text{ComplexMatrix entry}(i)))$$

Where, for a complex number

$$C = a + bj$$

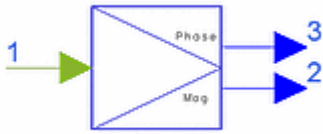
the abs() function is defined as

$$\text{abs}(C) = \sqrt{a^2 + b^2}$$

The complex entries are not converted by discarding the imaginary component as might be expected.

2. For general information regarding signal converter components, refer to the *About Signal Converters* (sigconverters).

## CxToPolar



**Description** Complex to Magnitude and Phase

**Library** Signal Converters

**Class** SDFCxToPolar

**C++ Code**

### Pin Inputs

Pin	Name	Description	Signal Type
1	input		complex

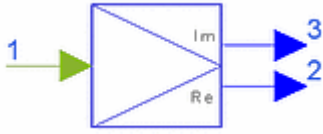
### Pin Outputs

Pin	Name	Description	Signal Type
2	magnitude		real
3	phase		real

### Notes/Equations

- CxToPolar outputs the magnitude and angle of a complex number:  
 $\text{Mag} = |\text{input}|$   
 $\text{Phase} = \angle \text{input}$  (the angle is in radians)
- For general information regarding signal converter components, refer to the *About Signal Converters* (sigconverters).

## CxToRect



**Description** Complex to Real and Imaginary

**Library** Signal Converters

**Class** SDFCxToRect

**C++ Code**

### Pin Inputs

Pin	Name	Description	Signal Type
1	input		complex

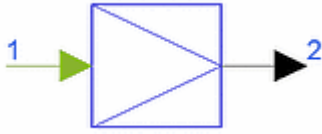
### Pin Outputs

Pin	Name	Description	Signal Type
2	real		real
3	imag		real

### Notes/Equations

1. CxToRect splits the input complex signal into its real (Re) and imaginary (Im) parts.

## CxToTimed



**Description** Complex to Timed

**Library** Signal Converters

**Class** TSDFCxToTimed

### Parameters

Name	Description	Default	Unit	Type	Range
TStep	output time step	0.0	sec	real	[0, ∞)
FCarrier	output carrier frequency	1.0e9	Hz	real	(0, ∞)

### Pin Inputs

Pin	Name	Description	Signal Type
1	input	input signal	complex

### Pin Outputs

Pin	Name	Description	Signal Type
2	output	output signal	timed

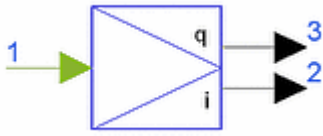
### Parameters

Name	Description	Value Range
TStep	output time step	[0, +∞)
FCarrier	output carrier frequency	(0, +∞)

### Notes/Equations

- CxToTimed converts a complex signal  $x [ n ]$  to a timed signal  $y [ nT ]$ , where  $T$  is equal to TStep.  
Given the complex number  $(a + jb)$  at input, the output is a complex envelope timed signal  $((I + jQ), fc)$  where  $I = a$ ,  $Q = b$ , and  $fc = \text{FCarrier}$ . Effectively, this converter is a modulator.
- The timed output pin has an effective output resistance of 0 ohm.
- Before the ADS 2002C release, this component enabled FCarrier to be 0 generating a complex envelope signal with characterization frequency equal to 0. Beginning with the ADS2002C release, FCarrier accepts positive values only. To assign a timestamp to a numeric complex signal so that it can be stored in a TimedSink and plotted in the data display with time as the X-axis, set FCarrier to any positive value.
- For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

## CxToTimedIQ



**Description** complex to baseband timed I and Q

**Library** Signal Converters

**Class** TSDFCxToTimedIQ

### Parameters

Name	Description	Default	Unit	Type	Range
TStep	output time step	0.0	sec	real	[0, $\infty$ )

### Pin Inputs

Pin	Name	Description	Signal Type
1	input	input signal	complex

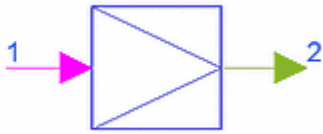
### Pin Outputs

Pin	Name	Description	Signal Type
2	Iout	output I baseband signal	timed
3	Qout	output Q baseband signal	timed

### Notes/Equations

1. CxToTimedIQ converts a complex input signal to two timed baseband signals. The time step of the output signals is specified by the TStep parameter. The real part of the input signal is output at the Iout pin; the imaginary part of the input signal is output at the Qout pin. This converter is equivalent to a CxToRect converter followed by a FloatIQToTimedIQ converter.
2. The timed output pins have an effective output resistance of 0 ohm.
3. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

## FixToCx



**Description** Fixed-Point to Complex

**Library** Signal Converters

**Class** SDFFixToCx

**C++ Code**

### Pin Inputs

Pin	Name	Description	Signal Type
1	input	Input fix type	fix

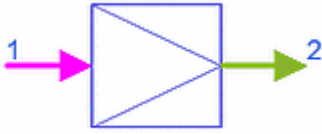
### Pin Outputs

Pin	Name	Description	Signal Type
2	output	Output complex type	complex

### Notes/Equations

1. FixToCx converts a fixed-point input to a complex output. The conversion results in a complex number with the real part the double-precision representation of the fixed-point input and imaginary part equal to 0.
2. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

## FixToCx\_M



**Description** Fixed-Point to Complex Matrix

**Library** Signal Converters

**Class** SDFFixToCx\_M

**Derived From** MatrixBase

### Pin Inputs

Pin	Name	Description	Signal Type
1	input		fix matrix

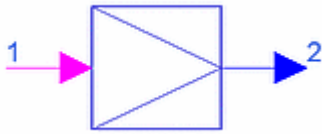
### Pin Outputs

Pin	Name	Description	Signal Type
2	output		complex matrix

### Notes/Equations

1. FixToCx\_M converts an input fixed-point matrix to a complex matrix. The conversion results in a complex matrix with real value entries that are the double-precision representation of each corresponding entry of the fixed-point matrix. The imaginary values of the resulting complex matrix are 0.
2. For general information regarding signal converter components, refer to the *About Signal Converters* (sigconverters).

## FixToFloat



**Description** Fixed-Point to Floating-Point

**Library** Signal Converters

**Class** SDFFixToFloat

**C++ Code**

### Pin Inputs

Pin	Name	Description	Signal Type
1	input	Input fix type	fix

### Pin Outputs

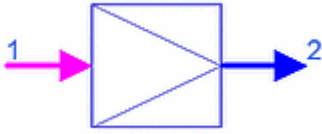
Pin	Name	Description	Signal Type
2	output	Output float type	real

### Notes/Equations

1. FixToFloat converts a fixed-point input to a floating-point (real) output.
2. For general information regarding signal converter components, refer to the *About Signal Converters* (sigconverters).



## FixToFloat\_M



**Description** Fixed-Point to Floating-Point Matrix

**Library** Signal Converters

**Class** SDFFixToFloat\_M

**Derived From** MatrixBase

### Pin Inputs

Pin	Name	Description	Signal Type
1	input		fix matrix

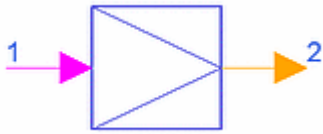
### Pin Outputs

Pin	Name	Description	Signal Type
2	output		real matrix

### Notes/Equations

1. FixToFloat\_M converts a fixed-point matrix to a floating-point (real) matrix. The conversion results in a floating-point (real) matrix with entries that are the double-precision representation of each corresponding entry of the fixed-point matrix.
2. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

## FixToInt



**Description** Fixed-Point to Integer

**Library** Signal Converters

**Class** SDFFixToInt

**C++ Code**

### Pin Inputs

Pin	Name	Description	Signal Type
1	input	Input fix type	fix

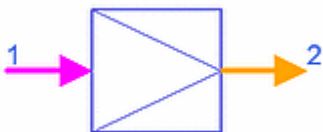
### Pin Outputs

Pin	Name	Description	Signal Type
2	output	Output int type	int

### Notes/Equations

1. FixToInt converts a fixed-point input to an integer output.
2. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

## FixToInt\_M



**Description** Fixed-Point to Integer Matrix

**Library** Signal Converters

**Class** SDFFixToInt\_M

**Derived From** MatrixBase

### Pin Inputs

Pin	Name	Description	Signal Type
1	input		fix matrix

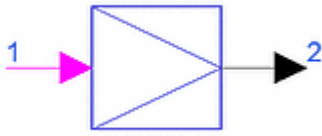
### Pin Outputs

Pin	Name	Description	Signal Type
2	output		int matrix

### Notes/Equations

1. FixToInt\_M converts a fixed-point matrix and to an integer matrix. The conversion results in a integer matrix with entries that are the integer representation of each corresponding entry of the fixed-point matrix.
2. For general information regarding signal converter components, refer to the *Introduction* (sigconverters).

## FixToTimed



**Description** Fixed-Point to Timed

**Library** Signal Converters

**Class** TSDFFixToTimed

### Parameters

Name	Description	Default	Unit	Type	Range
TStep	output time step	0.0	sec	real	[0, ∞)

### Pin Inputs

Pin	Name	Description	Signal Type
1	input		fix

### Pin Outputs

Pin	Name	Description	Signal Type
2	output		timed

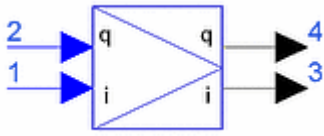
### Parameters

Name	Description	Value Range
TStep	output time step	[0, +∞)

### Notes/Equations

1. FixToTimed converts a fixed-point input signal  $x [ n ]$  to a timed signal  $y [ nT ]$  where  $T$  is equal to TStep. The output  $y$  is a real baseband timed signal.
2. The timed output pin has an effective output resistance of 0 ohm.
3. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

## FloatIQToTimedIQ



**Description** floating-point I and Q to baseband timed I and Q

**Library** Signal Converters

**Class** TSDFFloatIQToTimedIQ

### Parameters

Name	Description	Default	Unit	Type	Range
TStep	output time step	0.0	sec	real	[0, $\infty$ )

### Pin Outputs

Pin	Name	Description	Signal Type
1	Iin	input I signal	real
2	Qin	input Q signal	real

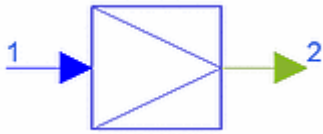
### Pin Inputs

Pin	Name	Description	Signal Type
3	Iout	output I signal	timed
4	Qout	output Q signal	timed

### Notes/Equations

- FloatIQToTimedIQ converts the two floating-point (real) input signals to two timed baseband signals. The time step of the output signals is specified by the TStep parameter. The floating-point (real) input signal at pin Iin is converted to a timed baseband signal at pin Iout and the floating-point (real) input signal at pin Qin is converted to a timed baseband signal at pin Qout. This converter is equivalent to two FloatToTimed converters in parallel (one connected between pins Iin and Iout and the other connected between pins Qin and Qout).
- The timed output pins have an effective output resistance of 0 ohm.
- For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

## FloatToCx



**Description** Floating-Point to Complex

**Library** Signal Converters

**Class** SDFFloatToCx

**C++ Code**

### Pin Inputs

Pin	Name	Description	Signal Type
1	input	Input float type	real

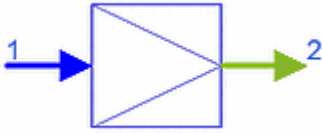
### Pin Outputs

Pin	Name	Description	Signal Type
2	output	Output complex type	complex

### Notes/Equations

1. FloatToCx converts a floating-point (real) input to a complex output. The conversion results in a complex number with the real part equal to input and imaginary part equal to 0.
2. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

## FloatToCx\_M



**Description** Floating-Point to Complex Matrix

**Library** Signal Converters

**Class** SDFFloatToCx\_M

**Derived From** MatrixBase

### Pin Inputs

Pin	Name	Description	Signal Type
1	input		real matrix

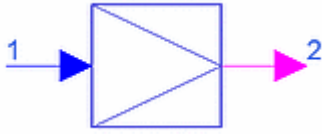
### Pin Outputs

Pin	Name	Description	Signal Type
2	output		complex matrix

### Notes/Equations

1. FloatToCx\_M converts a floating-point (real) matrix to a complex matrix. The conversion results in a complex matrix with real value entries that are the corresponding entries of the floating-point (real) matrix. The imaginary values of the resulting complex matrix are 0.
2. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

# FloatToFix



**Description** Floating-Point to Fixed-Point

**Library** Signal Converters

**Class** SDFFloatToFix

**Derived From** SDFFix

**C++ Code**

## Parameters

Name	Description	Default	Type
OverflowHandler	output overflow characteristic: wrapped, saturate, zero_saturate, warning	wrapped	enum
ReportOverflow	simulation overflow error report option: DONT_REPORT, REPORT	REPORT	enum
RoundFix	fixed-point computations, assignments, and data type conversions option: TRUNCATE, ROUND	TRUNCATE	enum
OutputPrecision	precision of output in bits and accumulation	2.14	precision

## Pin Inputs

Pin	Name	Description	Signal Type
1	input	Input float type	real

## Pin Outputs

Pin	Name	Description	Signal Type
2	output	Output fix type	fix

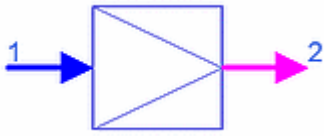
## Notes/Equations

1. FloatToFix converts a floating-point (real) input to a fixed-point output with the given OutputPrecision.
2. If the fixed-point operations cannot fit into the precision specified, overflow occurs with the overflow characteristic specified by OverflowHandler. If ReportOverflow = REPORT, after the simulation has finished the number of overflow errors (if any) is reported. RoundFix identifies whether fixed-point calculations are truncate or round method.  
For details, refer to Parameters for Fixed Point Components, in the *ADS Ptolemy Simulation* documentation.
3. This component uses twos-complement arithmetic; OutputPrecision parameter values must specify at least one bit to the left of the decimal place (used as a sign bit).
4. If unsigned arithmetic is desired, use a FloatToFixSyn component instead of FloatToFix.



5. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

## FloatToFix\_M



**Description** Floating-Point to Fixed-Point Matrix

**Library** Signal Converters

**Class** SDFFloatToFix\_M

**Derived From** SDFFix

### Parameters

Name	Description	Default	Type
OverflowHandler	output overflow characteristic: wrapped, saturate, zero_saturate, warning	wrapped	enum
ReportOverflow	simulation overflow error report option: DONT_REPORT, REPORT	REPORT	enum
RoundFix	fixed-point computations, assignments, and data type conversions option: TRUNCATE, ROUND	TRUNCATE	enum
OutputPrecision	precision of output in bits and accumulation	2.14	precision

### Pin Inputs

Pin	Name	Description	Signal Type
1	input		real matrix

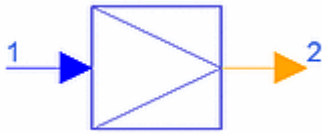
### Pin Outputs

Pin	Name	Description	Signal Type
2	output		fix matrix

### Notes/Equations

1. FloatToFix\_M converts a floating-point (real) matrix to a fixed-point matrix by converting the floating-point numbers in the input matrix to fixed-point numbers with the given OutputPrecision.
2. If the fixed-point operations cannot fit into the precision specified, overflow occurs with the overflow characteristic specified by OverflowHandler. If ReportOverflow = REPORT, after the simulation has finished the number of overflow errors (if any) is reported. RoundFix identifies whether fixed-point calculations are truncate or round method.  
For details, refer to *Parameters for Fixed-Point Components* (ptolemy) in the *ADS Ptolemy Simulation* documentation.
3. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

# FloatToInt



**Description** Floating-Point to Integer

**Library** Signal Converters

**Class** SDFFloatToInt

**C++ Code**

## Pin Inputs

Pin	Name	Description	Signal Type
1	input	Input float type	real

## Pin Outputs

Pin	Name	Description	Signal Type
2	output	Output int type	int

## Notes/Equations

- FloatToInt converts a floating-point (real) input to an integer output. The conversion occurs by taking the integer portion (truncating the fractional part) of the floating-point number. For example:

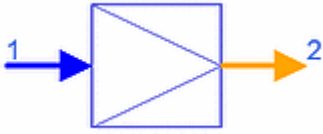
1.1, 1.221, 1.5, 1.673, 1.8961, and 1.974 are all converted to 1;

-2.03, -2.324, -2.59, -2.71, -2.85, and -2.97 are all converted to -2.

- For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

anchor:1105296:TopicAlias:FloatToInt\_M}

## FloatToInt\_M



**Description** Floating-Point to Integer Matrix

**Library** Signal Converters

**Class** SDFFloatToInt\_M

**Derived From** MatrixBase

### Pin Inputs

Pin	Name	Description	Signal Type
1	input		real matrix

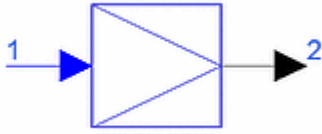
### Pin Outputs

Pin	Name	Description	Signal Type
2	output		int matrix

### Notes/Equations

1. FloatToInt\_M converts a floating-point (real) matrix to an integer matrix. The conversion results in an integer matrix with entries that are the integer portion of each corresponding entry of the floating-point (real) matrix.
2. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

# FloatToTimed



**Description** Floating-Point to Timed

**Library** Signal Converters

**Class** TSDFFloatToTimed

## Parameters

Name	Description	Default	Unit	Type	Range
TStep	output time step	0.0	sec	real	[0, ∞)

## Pin Inputs

Pin	Name	Description	Signal Type
1	input	input signal	real

## Pin Outputs

Pin	Name	Description	Signal Type
2	output	output signal	timed

## Notes/Equations

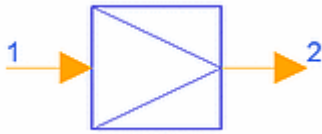
1. FloatToTimed converts a floating-point (real) signal to a timed signal. Given the floating-point (real) number  $x [ n ]$  at input, the output is a real baseband timed signal  $y ( t )$  with

$$y ( nT ) = x [ n ]$$

where  $T$  is the input signal time step and  $n = 1, 2, \dots$

2. The timed output pin has an effective output resistance of 0 ohm.
3. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

## IntToBits



**Description** Integer to Bits

**Library** Signal Converters

**Class** SDFIntToBits

**C++ Code**

### Parameters

Name	Description	Default	Type	Range
nBits	number of bits written per execution	4	int	[1, ∞)

### Pin Inputs

Pin	Name	Description	Signal Type
1	input		int

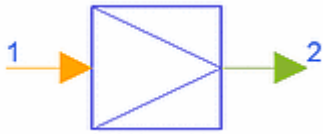
### Pin Outputs

Pin	Name	Description	Signal Type
2	output		int

### Notes/Equations

1. IntToBits reads the least significant nBits from an integer input, and outputs the bits as integers serially on the output, most significant bit first.
2. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

## IntToCx



Description\* Integer to Complex

**Library** Signal Converters

**Class** SDFIntToCx

**C++ Code**

### Pin Inputs

Pin	Name	Description	Signal Type
1	input	Input integer type	int

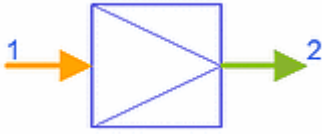
### Pin Outputs

Pin	Name	Description	Signal Type
2	output	Output complex type	complex

### Notes/Equations

1. IntToCx converts an integer input to a complex output. The conversion results in a complex number with the real part equal to double-precision representation of input and the imaginary part equal to 0.
2. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

## IntToCx\_M



**Description** Integer to Complex Matrix

**Library** Signal Converters

**Class** SDFIntToCx\_M

**Derived From** MatrixBase

### Pin Inputs

Pin	Name	Description	Signal Type
1	input		int matrix

### Pin Outputs

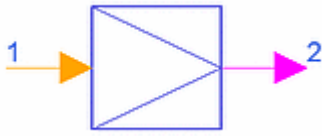
Pin	Name	Description	Signal Type
2	output		complex matrix

### Notes/Equations

1. IntToCx\_M converts an input integer matrix to a complex matrix, where real value entries are the double-precision representation of the corresponding entries of the integer matrix. The imaginary values of the resulting complex matrix are 0.
2. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).



# IntToFix



Description\* Integer to Fixed-Point

**Library** Signal Converters

**Class** SDFIntToFix

**Derived From** SDFFix

**C++ Code**

## Parameters

Name	Description	Default	Type
OverflowHandler	output overflow characteristic: wrapped, saturate, zero_saturate, warning	wrapped	enum
ReportOverflow	simulation overflow error report option: DONT_REPORT, REPORT	REPORT	enum
RoundFix	fixed-point computations, assignments, and data type conversions option: TRUNCATE, ROUND	TRUNCATE	enum
OutputPrecision	precision of output in bits and accumulation	16.0	precision

## Pin Inputs

Pin	Name	Description	Signal Type
1	input	Input integer type	int

## Pin Outputs

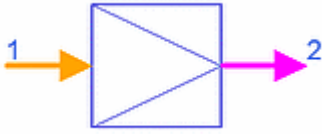
Pin	Name	Description	Signal Type
2	output	Output fix type	fix

## Notes/Equations

1. IntToFix converts an integer input to a fixed-point output with the given OutputPrecision.
2. If fixed-point operations cannot fit into the precision specified, overflow occurs with the characteristic specified by OverflowHandler. If ReportOverflow = REPORT, the number of overflow errors (if any) is reported after simulation. RoundFix identifies whether fixed-point calculations are truncate or round. For details, refer to *Parameters for Fixed-Point Components* (ptolemy) in the *ADS Ptolemy Simulation* documentation.
3. This component uses twos-complement arithmetic; OutputPrecision parameter values must specify at least one bit to the left of the decimal place (used as a sign bit).
4. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).



## IntToFix\_M



**Description** Integer to Fixed-Point Matrix

**Library** Signal Converters

**Class** SDFIntToFix\_M

**Derived From** SDFFix

### Parameters

Name	Description	Default	Type
OverflowHandler	output overflow characteristic: wrapped, saturate, zero_saturate, warning	wrapped	enum
ReportOverflow	simulation overflow error report option: DONT_REPORT, REPORT	REPORT	enum
RoundFix	fixed-point computations, assignments, and data type conversions option: TRUNCATE, ROUND	TRUNCATE	enum
OutputPrecision	precision of output in bits and accumulation	16.0	precision

### Pin Inputs

Pin	Name	Description	Signal Type
1	input		int matrix

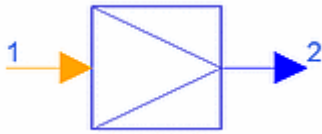
### Pin Outputs

Pin	Name	Description	Signal Type
2	output		fix matrix

### Notes/Equations

1. IntToFix\_M converts an input integer matrix to a fixed-point matrix by converting the integer numbers in the input matrix to fixed-point numbers with the given OutputPrecision.
2. If fixed-point operations cannot fit into the precision specified, overflow occurs with the characteristic specified by OverflowHandler. If ReportOverflow = REPORT, the number of overflow errors (if any) is reported after simulation. RoundFix identifies whether fixed-point calculations are truncate or round. For details, refer to *Parameters for Fixed-Point Components* (ptolemy) in the *ADS Ptolemy Simulation* documentation.
3. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

## IntToFloat



**Description** Integer to Floating-Point

**Library** Signal Converters

**Class** SDFIntToFloat

**C++ Code**

### Pin Inputs

Pin	Name	Description	Signal Type
1	input	Input integer type	int

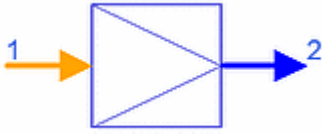
### Pin Outputs

Pin	Name	Description	Signal Type
2	output	Output float type	real

### Notes/Equations

1. IntToFloat converts an integer input to a floating-point (real) output.
2. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

## IntToFloat\_M



**Description** Integer to Floating-Point Matrix

**Library** Signal Converters

**Class** SDFIntToFloat\_M

**Derived From** MatrixBase

### Pin Inputs

Pin	Name	Description	Signal Type
1	input		int matrix

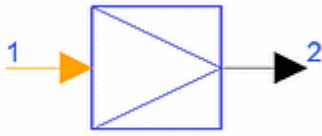
### Pin Outputs

Pin	Name	Description	Signal Type
2	output		real matrix

### Notes/Equations

1. IntToFloat\_M converts an input integer matrix to a floating-point (real) matrix, where each element of the output matrix is the double-precision floating-point representation of the corresponding element in the input matrix.
2. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

## IntToTimed



**Description** Integer to Timed

**Library** Signal Converters

**Class** TSDFIntToTimed

### Parameters

Name	Description	Default	Unit	Type	Range
TStep	output time step	0.0	sec	real	$[0, \infty)$

### Pin Inputs

Pin	Name	Description	Signal Type
1	input	input signal	int

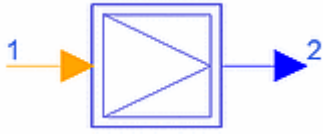
### Pin Outputs

Pin	Name	Description	Signal Type
2	output	output signal	timed

### Notes/Equations

1. IntToTimed converts an integer signal to a timed signal. Given the integer number  $x [ n ]$  at input, the output is a real baseband timed signal  $y ( t )$  with  $y ( nT ) = x [ n ]$  where  $T$  is the input signal time step and  $n = 1, 2, \dots$
2. The timed output pin has an effective output resistance of 0 ohm.
3. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

# LogicToNRZ



**Description** Logic to NRZ Format

**Library** Signal Converters

**Class** SDFLogicToNRZ

## Parameters

Name	Description	Default	Type	Range
Amplitude	amplitude of NRZ signal	1.0	real	$(-\infty, \infty)$

## Pin Inputs

Pin	Name	Description	Signal Type
1	input		int

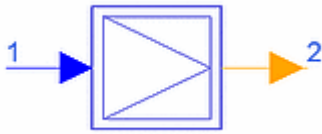
## Pin Outputs

Pin	Name	Description	Signal Type
2	output		real

## Notes/Equations

1. Converts a logic level to NRZ level. An input Logic 0 produces a -Amplitude output; an input Logic 1 produces a +Amplitude output.
2. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

## NRZToLogic



**Description** NRZ to Logic Format

**Library** Signal Converters

**Class** SDFNRZToLogic

### Parameters

Name	Description	Default	Type	Range
Amplitude	Amplitude	1.0	real	$(-\infty, \infty)$

### Pin Inputs

Pin	Name	Description	Signal Type
1	input		real

### Pin Outputs

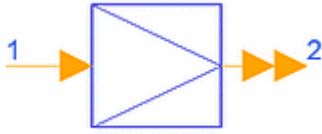
Pin	Name	Description	Signal Type
2	output		int

### Notes/Equations

1. Converts an NRZ level to Logic level. An input  $\geq 0$  produces an output Logic 1; an input  $< 0$  produces an output Logic 0.
2. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).



## NumToBus



**Description** Number to Bus

**Library** Signal Converters

**Class** SDFNumToBus

**C++ Code**

### Pin Inputs

Pin	Name	Description	Signal Type
1	input		int

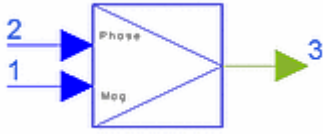
### Pin Outputs

Pin	Name	Description	Signal Type
2	output		multiple int

### Notes/Equations

1. NumToBus converts an integer to binary form in terms of bits to be output on the parallel bus. The most significant bit is the sign bit. The output can be observed by connecting a BusSplit component.  
For example, integer values from 0 to 7 are input. BusSplit4 is used to access the 4 output bits. Then integer values 0 to 7 are converted into the binary forms of 0000, 0001, 0010, 0011, 0100, 0101, 0110, and 0111.
2. Also see: BusSplit components
3. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

## PolarToCx



**Description** Magnitude and Phase to Complex

**Library** Signal Converters

**Class** SDFPolarToCx

**C++ Code**

### Pin Inputs

Pin	Name	Description	Signal Type
1	magnitude		real
2	phase		real

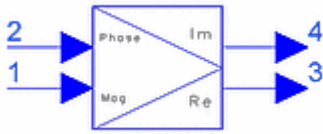
### Pin Outputs

Pin	Name	Description	Signal Type
3	output		complex

### Notes/Equations

1. PolarToCx converts a complex number from its polar representation to its Cartesian form. The angle must be specified in radians.
2. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

## PolarToRect



Description\* Magnitude and Phase to Rectangular

**Library** Signal Converters

**Class** SDFPolarToRect

**C++ Code**

### Pin Inputs

Pin	Name	Description	Signal Type
1	magnitude		real
2	phase		real

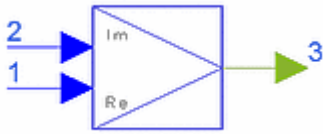
### Pin Outputs

Pin	Name	Description	Signal Type
3	x		real
4	y		real

### Notes/Equations

1. PolarToRect converts two floating-point (real) inputs representing a complex number in polar form to two floating-point (real) outputs representing a complex number in the rectangular form. The phase is assumed to be in radians.
2. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

## RectToCx



**Description** Real and Imaginary to Complex

**Library** Signal Converters

**Class** SDFRectToCx

**C++ Code**

### Pin Inputs

Pin	Name	Description	Signal Type
1	real		real
2	imag		real

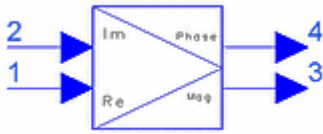
### Pin Outputs

Pin	Name	Description	Signal Type
3	output		complex

### Notes/Equations

1. RectToCx converts its real (Re) and imaginary (Im) inputs to a complex output.
2. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

# RectToPolar



**Description** Rectangular to Polar

**Library** Signal Converters

**Class** SDFRectToPolar

**C++ Code**

## Pin Inputs

Pin	Name	Description	Signal Type
1	x		real
2	y		real

## Pin Outputs

Pin	Name	Description	Signal Type
3	magnitude		real
4	phase		real

## Notes/Equations

1. RectToPolar converts two floating-point (real) inputs representing a complex number in rectangular form to two floating-point (real) outputs representing a complex number in polar form (magnitude and phase). The phase output is in the range  $-\pi$  to  $\pi$ .
2. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

# RFtoPower



**(Description** RF signal envelope to power converter

**Library** Signal Converters

**Class** TSDFRFtoPower

## Parameters

Name	Description	Default	Unit	Type	Range
RefR	RF signal reference resistance	50	Ohm	real	(0, ∞)
NumStart	sample number to start integration for power in watts	0		int	[0, ∞)

## Pin Inputs

Pin	Name	Description	Signal Type
1	Env	RF signal complex envelope	complex

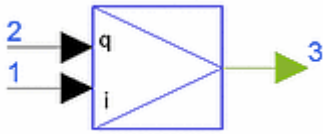
## Pin Outputs

Pin	Name	Description	Signal Type
2	P	power value in watts	real

## Notes/Equations

1. RFtoPower converts an input complex signal representing an RF signal I, Q envelope to average power in Watts.
2. The input RF complex envelope is squared and divided by  $2 \times \text{RefR}$  to obtain the instantaneous power.
3. Output P is the integrated instantaneous power (with integration beginning as sample NumStart) divided by the number of samples recorded.
4. Use of this component is demonstrated in (access from ADS Main window) *File > Open > Example > PtolemyDocExamples > Timed\_RF\_Subsystems\_wrk\_*. Open the networks design *RF\_PAE\_example* and push into *RF\_PAE\_TestFixture* that uses RFtoPower.
5. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

# TimedIQToCx



**Description** baseband timed I and Q to complex

**Library** Signal Converters

**Class** TSDFTimedIQToCx

## Pin Inputs

Pin	Name	Description	Signal Type
1	Iin	input I baseband signal	timed
2	Qin	input Q baseband signal	timed

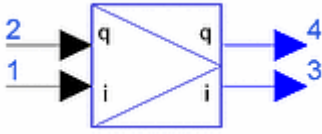
## Pin Outputs

Pin	Name	Description	Signal Type
3	output	output signal	complex

## Notes/Equations

1. TimedIQToCx converts the two timed baseband input signals to a complex signal. The signal at pin Iin becomes the real part of the complex output signal and the signal at pin Qin becomes the imaginary part of the complex output signal. This converter is equivalent to a TimedIQToFloatIQ converter followed by a RectToCx converter.
2. This component has infinite input impedance.
3. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

## TimedIQToFloatIQ



**Description** baseband timed I and Q to floating-point I and Q

**Library** Signal Converters

**Class** TSDFTimedIQToFloatIQ

### Pin Inputs

Pin	Name	Description	Signal Type
1	Iin	input I signal	timed
2	Qin	input Q signal	timed

### Pin Outputs

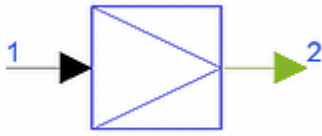
Pin	Name	Description	Signal Type
3	Iout	output I signal	real
4	Qout	output Q signal	real

### Notes/Equations

1. TimedIQToFloatIQ converts the two timed baseband input signals to two floating-point (real) signals. The timed baseband input signal at pin Iin is converted to a floating-point (real) signal at pin Iout and the timed baseband input signal at pin Qin is converted to a floating-point (real) signal at pin Qout. This converter is equivalent to two TimedToFloat converters in parallel (one connected between pins Iin and Iout and the other connected between pins Qin and Qout). The difference between this converter and a pair of TimedToFloat converters in parallel is that the TimedToFloat converters can accept timed RF and signals and convert them to floating-point (real) signals, where the TimedIQToFloatIQ converter accepts timed baseband signals only at its inputs.
2. This component has infinite input impedance.
3. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).



## TimedToCx



**Description** Timed to Complex

**Library** Signal Converters

**Class** TSDFTimedToCx

### Pin Inputs

Pin	Name	Description	Signal Type
1	input	input signal	timed

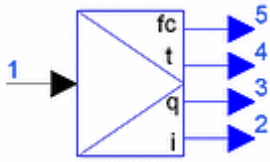
### Pin Outputs

Pin	Name	Description	Signal Type
2	output	output signal	complex

### Notes/Equations

1. TimedToCx converts a timed signal to a complex signal. If the timed signal is a complex envelope signal, the output is  $(I + jQ)$ . Likewise, when the timed signal is a real baseband signal, the output is the complex number  $(R + jS)$  where  $R$  is the real baseband signal and  $S$  is 0.
2. This component has infinite input impedance.
3. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

## TimedToData



**Description** Timed to data: i, q, time, fc

**Library** Signal Converters

**Class** TSDFTimedToData

### Pin Inputs

Pin	Name	Description	Signal Type
1	input	input signal	timed

### Pin Outputs

Pin	Name	Description	Signal Type
2	i	i envelope	real
3	q	q envelope	real
4	t	time	real
5	fc	characterization frequency	real

### Notes/Equations

1. TimedToData converts a timed input signal  $x(t)$  to its constituent data members  $\{i, q, t, F_c\}$ . An input timed RF signal is represented as:

$$x(t) = I(t) \cos(2\pi F_c t) - Q(t) \sin(2\pi F_c t)$$

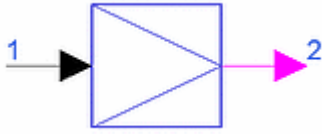
An input baseband timed signal is simply:

$$x(t) = I(t)$$

with  $Q = 0$  and  $F_c = 0$ .

2. This component has infinite input impedance.
3. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

# TimedToFix



**Description** Timed to Fixed

**Library** Signal Converters

**Class** TSDFTimedToFix

**Derived From** TSDFFix

## Parameters

Name	Description	Default	Type
OverflowHandler	output overflow characteristic: wrapped, saturate, zero_saturate, warning	wrapped	enum
ReportOverflow	simulation overflow error report option: DONT_REPORT, REPORT	REPORT	enum
RoundFix	fixed-point calculations, assignments, and data type conversion option: TRUNCATE, ROUND	TRUNCATE	enum
OutputPrecision	precision of output in bits and accumulation	2.14	precision

## Pin Inputs

Pin	Name	Description	Signal Type
1	input		timed

## Pin Outputs

Pin	Name	Description	Signal Type
2	output		fix

## Notes/Equations

- TimedToFix converts a timed input signal  $x(t) = \{I(t), Q(t), F_c\}$  (either baseband or complex envelope flavors) to a fixed-point output  $y[n]$  with the given OutputPrecision. The conversion rule is for complex envelope:

$$y[n] = (\text{fix})\{I(nT) \times \cos(2\pi F_c nT) - Q(nT) \times \sin(2\pi F_c nT)\}$$

where  $T$  is the input signal time step

for baseband:

$$y[n] = (\text{fix})\{x(nT)\}$$

where  $T$  is the input signal time step

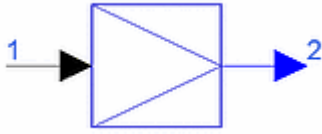
- If the fixed-point operations cannot fit into the precision specified, overflow occurs with the overflow characteristic specified by OverflowHandler. If ReportOverflow = REPORT, after the simulation has finished the number of overflow errors (if any) is

reported. RoundFix identifies whether fixed-point calculations are truncate or round method.

For details, refer to *Parameters for Fixed-Point Components* (ptolemy) in the *ADS Ptolemy Simulation* documentation.

3. This component uses twos-complement arithmetic; OutputPrecision values must specify at least 1 bit to the left of the decimal place (used as a sign bit).
4. This component has infinite input impedance.
5. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

# TimedToFloat



**Description** Timed to Floating-Point

**Library** Signal Converters

**Class** TSDFTimedToFloat

## Pin Inputs

Pin	Name	Description	Signal Type
1	input	input signal	timed

## Pin Outputs

Pin	Name	Description	Signal Type
2	output	output signal	real

## Notes/Equations

1. TimedToFloat converts a timed input signal  $x(t) = \{I(t), Q(t), F_c\}$  to a floating-point (real). The conversion rule is:  
for complex envelope:

$$y[n] = I(nT) \times \cos(2\pi F_c nT) - Q(nT) \times \sin(2\pi F_c nT)$$

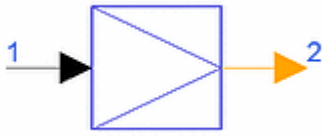
where  $T$  is the input signal time step  
for baseband:

$$y[n] = x(nT)$$

where  $T$  is the input signal time step

2. This component has infinite input impedance.
3. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

## TimedToInt



**Description** Timed to Integer

**Library** Signal Converters

**Class** TSDFTimedToInt

### Pin Inputs

Pin	Name	Description	Signal Type
1	input	input signal	timed

### Pin Outputs

Pin	Name	Description	Signal Type
2	output	output signal	int

### Notes/Equations

1. TimedToInt converts a timed input signal  $x(t) = \{I(t), Q(t), F_c\}$  to an integer output  $y[n]$ . The conversion rule is:  
for complex envelope:

$$y[n] = (int)\{I(nT) \times \cos(2\pi F_c nT) - Q(nT) \times \sin(2\pi F_c nT)\}$$

where  $T$  is the input signal time step

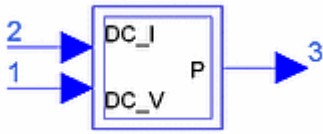
for baseband:

$$y[n] = (int)\{x(nT)\}$$

where  $T$  is the input signal time step

2. This component has infinite input impedance.
3. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).

## VitoPower



**Description** Baseband voltage and current signal to power converter

**Library** Signal Converters

**Class** TSDFVitoPower

### Parameters

Name	Description	Default	Type	Range
NumStart	sample number to start integration for power in watts	0	int	[0, ∞)

### Pin Inputs

Pin	Name	Description	Signal Type
1	V	voltage value	real
2	I	current value	real

### Pin Outputs

Pin	Name	Description	Signal Type
3	P	power value in watts	real

### Notes/Equations

1. VitoPower converts input values representing voltage and current to average power in Watts.
2. Inputs V and I are multiplied to obtain the instantaneous power.
3. Output P is the integrated instantaneous power (with integration beginning at sample NumStart) divided by the number of samples recorded.
4. Use of this component is demonstrated in (access from the ADS Main window) *File > Open > Example > PtolemyDocExamples > Timed\_RF\_Subsystems\_wrk\_*. Open the networks design *RF\_PAE\_example* and push into *RF\_PAE\_TestFixture* that uses VitoPower.
5. For general information regarding signal converter components, refer to *About Signal Converters* (sigconverters).